



## ON THE GEOMETRY OF SUBMERSIONS

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**Abstract.** In this paper we study the geometry of the level surfaces of functions of certain class. It is proved that the level surfaces of these functions generate a foliation whose leaves are manifolds of constant Gaussian curvature.

### 1. INTRODUCTION

Let  $M$  be a smooth Riemannian manifold of dimension  $n$  with Riemannian metric  $g$ ,  $F$ -foliation of dimension  $k$  on  $M$ , where  $0 < k < n$  [6]. We denote by  $L_p$  - a leaf of the foliation  $F$  passing through the point  $p \in M$ , by  $T_q F$  - the tangent space of leaf  $L_p$  at the point  $q \in L_p$ , and by  $H(q)$  - orthogonal complement of  $T_q F$ . As a result, we get two sub-bundles  $TF = \{T_q F\}$ ,  $TH = \{H(q)\}$  of the tangent bundle  $TM$ , and we have the orthogonal decomposition  $TM = TF \oplus H$ . Thus every vector field  $X$  expanded in the form  $X = X^v + X^h$ , where  $X^v \in TF$ ,  $X^h \in TH$ . If  $X^h = 0$  (respectively  $X^v = 0$ ), the field is called the vertical (horizontal) vector field.

The Riemannian metric  $g$  on a manifold  $M$  induces Riemannian metric  $\tilde{g}$  on the leaf  $L_p$ . Canonical injection  $i : L_p \rightarrow M$  is an isometric immersion with respect to these metrics. A connection  $\nabla$  (Levi-Civita connection) defined by the Riemannian metric  $g$  induces a connection  $\tilde{\nabla}$  on  $L_p$  which coincides with the connection defined by the Riemannian metric  $\tilde{g}$  [1].

Let  $Z$  be a horizontal vector field. For each vertical vector field  $X$  we define the vertical vector field

$$S(X, Z) = (\nabla_X Z)^v.$$

and we get the tensor field of type (1,1)

$$X, Z \rightarrow S_Z X = S(X, Z).$$

This tensor field gives the bilinear form  $l_Z(X, Y) = \langle S_Z X, Y \rangle$ , where  $\langle X, Y \rangle$  - the inner product defined by the Riemannian metric  $g$ .

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Tensor field  $S_Z$  is called the second fundamental tensor, and the form  $l_Z(X, Y)$  is called the second main form with respect to the horizontal field  $Z$ .

Mapping  $S_Z : T_q F \rightarrow T_q F$  defined by the formula  $X_q \rightarrow S(X, Z)_q$  is self-  
endomorphism with respect to the scalar product defined by the Riemannian  
metric  $\tilde{g}$ . If the vector field  $Z$  is a vector of unit length, the eigenvalues of  
this endomorphism called the principal curvatures of  $L_p$  at the point  $q$ , and  
the corresponding eigenvectors are called the principal directions.

The mean curvature  $H_Z$  and the Gauss-Kronecker curvature  $K_Z$  of the  
leaf  $L_p$  at the point  $q$  are determined by the principal curvatures [1]:

$$H_Z = \frac{1}{k} \text{tr} S_Z, K_Z = \det S_Z, \text{ where } k = n - m.$$

Let  $f : M \rightarrow B$  be a differentiable map of maximal rank, where  $M, B$  a  
smooth manifolds of dimensions respectively. Such maps are called submersions.  
By the theorem on the rank of a differentiable function for each point  
 $p \in B$  inverse image  $f^{-1}(p)$  is a submanifold of dimension  $k = n - m$ . Thus  
submersion  $f : M \rightarrow B$  generates a foliation on a manifold of dimension  
 $k = n - m$  whose leaves are submanifolds  $L_p = f^{-1}(p), p \in B$ .

The geometry and topology of the foliations generated by submersions  
were subject of numerous studies [2],[4],[5],[6].

If the differential  $df$  of mapping  $f : M \rightarrow B$  preserves the length of  
horizontal vectors, the submersion  $f : M \rightarrow B$  is called the Riemannian  
submersions. Geometry of Riemannian submersions investigated in numer-  
ous studies, in particular in [5] derived the fundamental equations of the  
Riemannian submersion.

## 2. MAIN RESULT

We consider the case where the manifold  $B$  is one-dimensional manifold,  
to be more precise we consider smooth function  $f : M \rightarrow R$ . If  $\text{Crit}\{f\}$  -  
the set of critical points of the function  $f$ , then on the manifold  $M \setminus \text{Crit}\{f\}$   
arises foliation  $F$  of dimension  $n - 1$  (or codimension one foliation), leaves  
of which are level surfaces of function  $f$ .

In [6] it is studied the geometry of the level surfaces of the functions for  
which  $X(|\text{grad}f|^2) = 0$  for each vertical vector field  $X$ . In particular, it is  
proved that the level surfaces form the so-called Riemannian foliation.

In this paper, we show that the level surfaces of the function of this class  
are the surfaces of constant Gaussian curvature.

**Theorem 2.1.** *Let  $f : M \rightarrow R$  be a smooth function. Suppose that  $\text{Crit}f = \emptyset$  and  $X(|\text{grad}f|^2) = 0$  for each vertical vector field  $X$ . Then every leaf of foliation  $F$  (level surface of  $f$ ) is a manifold of constant Gaussian curvature.*

*Proof.* As is known the Hessian is given by

$$h_f(X, Y) = l_Z(X, Y) = \langle \nabla_X Z, Y \rangle$$

where  $Z = \text{grad}f$ ,  $\nabla$ - the Levi-Civita connection defined by Riemannian  
metric  $g$ .

The map  $X \rightarrow h_f(X) = \nabla_X Z$  (Hesse tensor) is a linear operator and is given by a symmetric matrix  $A$ :

$$h_f(X) = \nabla_X Z = AX.$$

We denote by  $\chi(\lambda)$  the characteristic polynomial of the matrix  $A$  with a free term  $(-1)^n \det A$  and define a new polynomial  $\rho(\lambda)$  by the equation

$$\lambda\rho(\lambda) = \det A - (-1)^n \chi(\lambda).$$

Since  $\chi(A) = 0$  we have that  $A\rho(A) = \det A \cdot E$ , where  $E$  - is the identity matrix. The elements of the matrix  $\rho(A)$  are cofactors of the matrix  $A$ . This matrix is denoted by  $H_f^c$ .

It is well known that the Gaussian curvature of the surface is calculated by the formula ([1], p.110)

$$K = \det S = \frac{1}{|\text{grad}f|^{n+1}} \langle H_f^c(\text{grad}f), \text{grad}f \rangle.$$

To prove the theorem it suffices to show that  $X(K) = 0$  for each vertical vector field  $X$  at any point  $q$  of a leaf  $L_p$ .

By hypothesis of the theorem we have

$$X(|\text{grad}f|^2) = 0$$

and so

$$X\left(\frac{1}{|\text{grad}f|^{n+1}}\right) = 0$$

therefore we need to show that

$$\langle \nabla_X H_f^c Z, Z \rangle + \langle H_f^c Z, \nabla_X Z \rangle = 0.$$

We know that if  $X(|\text{grad}f|^2) = 0$  for each vertical vector field  $X$ , each gradient line of  $f$  is a geodesic line of Riemannian manifold [4]. By definition, the gradient line is a geodesic if and only if  $\nabla_N N = 0$ , where  $N = \frac{Z}{|Z|}$ .

We calculate the covariant differential

$$\nabla_N N = \frac{1}{|Z|} \nabla_Z N = \frac{1}{|Z|} \left( \frac{1}{|Z|} \nabla_Z Z + Z \left( \frac{1}{|Z|} \right) Z \right) = 0$$

and get  $\nabla_Z Z = \lambda Z$ , where  $\lambda = -|Z|Z\left(\frac{1}{|Z|}\right)$ . This means that the gradient vector  $Z$  is the eigenvector of matrix  $A$ .

Let  $X_1^0, X_2^0, \dots, X_{n-1}^0, Z^0$  - be mutually orthogonal eigenvectors of  $A$  at the point  $q \in L_p$  such that  $X_1^0, X_2^0, \dots, X_{n-1}^0$  the unit vectors,  $Z^0$  - the value of the gradient field at a point  $q$ . Locally, they can be extended to the vector fields  $X_1, X_2, \dots, X_{n-1}, Z$  to a neighborhood of (say  $U$ ) point  $q$  so that they formed at each point of an orthogonal basis consisting of eigenvectors. We construct the Riemannian normal system of coordinates  $(x_1, x_2, \dots, x_n)$  in a neighborhood  $U$  via vectors  $X_1^0, X_2^0, \dots, X_{n-1}^0, Z^0$  ([1], p.112).

The components  $g_{ij}$  of the metric  $g$  and the connection components  $\Gamma_{ij}^k$  in the normal coordinate system satisfies the conditions of ([1], p. 132):

$$g_{ij}(q) = \delta_{ij}, \Gamma_{ij}^k(q) = 0.$$

We show that  $X(\lambda) = 0$  for each vertical field  $X$ . From the equality

$$X(\lambda) = -X(|Z|)Z\left(\frac{1}{|Z|}\right) - |Z|X\left(Z\left(\frac{1}{|Z|}\right)\right)$$

and from the condition  $X(|Z|) = 0$  follows equality

$$X\left(Z\left(\frac{1}{|Z|}\right)\right) = X(Z(\phi)) = [X, Z](\phi) - Z(X(\phi))$$

where  $\phi = \frac{1}{|Z|}$ ,  $[X, Z]$ -Lie bracket of vector fields  $X, Z$ .

From the condition of the theorem follows  $X(Z(\phi)) = 0$ . In [6] it is shown that  $X(|gradf|^2) = 0$  for each of the vertical vector field  $X$  if and only if  $[X, Z]$  a vertical field. Therefore  $[X, Z](\phi) = 0$ . Thus,  $\lambda$  is a constant function on the leaf  $L$ .

Now we denote by  $\lambda_1, \lambda_2, \dots, \lambda_{n-1}$  the eigenvalues of the matrix  $A$  corresponding to the eigenvectors  $X_1, X_2, \dots, X_{n-1}$ . Then in the basis  $X_1, X_2, \dots, X_{n-1}, Z$  matrix  $A$  has the form:

$$A = \begin{pmatrix} \lambda_1 & 0 & \dots & 0 \\ 0 & \lambda_2 & \dots & 0 \\ \dots & \dots & \dots & \dots \\ 0 & 0 & \dots & \lambda_n \end{pmatrix}$$

By hypothesis of the theorem, the vector field  $\nabla_X Z$  is vertical field. It follows Codazzi equations have the form ([3], p.29)

$$(\nabla_X A)Y = (\nabla_Y A)X$$

From this equation we get

$$\nabla_{X_i} A X_j = \nabla_{X_j} A X_i, \nabla_{X_i} A Z = \nabla_Z A X_i \quad (1)$$

at any point of  $U$  for each vector field  $X_i$ . From first equation of (1) we take following equality

$$X_i(\lambda_j)X_j + \lambda_j \nabla_{X_i} X_j = X_j(\lambda_i)X_j + \lambda_i \nabla_{X_j} X_i. \quad (2)$$

Since  $\nabla_{X_i} X_j = \Gamma_{ij}^k X_k = 0$  at the point  $q$  by properties of normal coordinate system, from (2) follows equality

$$X_i(\lambda_j)X_j = X_j(\lambda_i)X_j. \quad (3)$$

By the linear independence  $X_1, X_2, \dots, X_{n-1}$ , we have that

$$X_i(\lambda_j) = 0 \text{ for } i \neq j \text{ for all } i.$$

From second equation of (1) we take following

$$X_i(\lambda)Z + \lambda \nabla_{X_i} Z = Z(\lambda_i)X_i + \lambda_i \nabla_Z X_i. \quad (4)$$

Since

$$\nabla_{X_i} Z = \nabla_Z X_i = 0$$

at the point  $q$  from the linear independence of vectors  $X_i, Z$  we have that

$$X_i(\lambda) = 0, Z(\lambda_i) = 0 \text{ for all } i.$$

On the other hand

$$\nabla_Z AX_i = Z(\lambda_i)X_i + \lambda_i \nabla_Z X_i, \nabla_{X_i} AZ = \nabla_Z AX_i, \nabla_{X_i} Z = \lambda_i X_i. \quad (5)$$

From (5) we get that

$$\lambda_i^2 X_i + Z(\lambda_i)X_i = X_i(\lambda)Z + \lambda \lambda_i X_i. \quad (6)$$

Since  $Z(\lambda_i) = 0, X_i(\lambda) = 0$  at the point  $q$  from the (6) follows that  $\lambda_i^2 = \lambda \lambda_i$ . In particular, this implies that if  $\lambda_i \neq 0$  then  $\lambda_i = \lambda$  and  $X(\lambda_i) = X(\lambda) = 0, Z(\lambda) = Z(\lambda_i) = 0$  for all  $i$ . Thus, in the neighborhood  $U$  of the point  $q$  non-zero eigenvalues of the matrix  $A$  are constant and equal  $\lambda$ .

Given this fact we compute  $X(K)$ . We denote by  $m$  the number of zero eigenvalues of  $A$ . If  $m = 0$ , all the eigenvalues are equal to the number  $\lambda$ . In this case, by the definition of the matrix  $H_f^c$  we get that  $H_f^c Z = \lambda^{n-1} Z$ .

Consider the case when  $m > 0$ . If  $m > 1$ , then  $H_f^c = 0$ . If  $m = 1$  than  $\lambda_i = 0$  for some  $i$  and  $AX_i = \nabla_{X_i} Z = 0$ . This means that the vector field  $Z$  is parallel along the integral curve of a vector field  $X_i$  (along  $i$ -coordinate line). If  $i = n$  we have  $\lambda = \lambda_i = 0$  for all  $i$  and  $H_f^c = 0$ .

Without loss of generality we assume that  $i < n$ . In this case vector  $H_f^c Z$  have only one nonzero component  $b_i$  and  $H_f^c Z = b_i \frac{\partial}{\partial x_i}$ . In this case we get

$$\nabla_X H_f^c Z = X(b_i) \frac{\partial}{\partial x_i} + b_i \nabla_X \frac{\partial}{\partial x_i}.$$

As we know that  $X_i = \frac{\partial}{\partial x_i}$  vertical and  $\nabla_X \frac{\partial}{\partial x_i} = 0$ . Thus in the case  $m = 1$  we have  $\langle \nabla_X H_f^c(\text{grad}f), \text{grad}f \rangle = 0$

Let us consider the case  $m = 0$ . In this case we have equalities  $H_f^c Z = \lambda^{n-1} Z$  and

$$\nabla_X H_f^c Z = X(\lambda^{n-1}) Z + \lambda^{n-1} \nabla_X Z.$$

As mentioned above field  $\nabla_X \text{grad}f$  is a vertical vector field for each vertical vector field  $X$  (the field  $AX$  is vertical). From this equalities follows  $\langle \nabla_X H_f^c(\text{grad}f), \text{grad}f \rangle = 0$  at the point  $q$ . The theorem is proved.

Examples:

1.  $M = R^3 \setminus \{(x, y, z) : x = 0, y = 0\}, f(x, y, z) = x^2 + y^2$ . Level surfaces of this submersion are manifolds of zero Gaussian curvature.

2.  $M = R^3 \setminus \{(0, 0, 0), f(x, y, z) = x^2 + y^2 + z^2$ . Level surfaces of this submersion are manifolds of constant positive Gaussian curvature.

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